

Monkey bias with velocity consistency relation

Sora Yamashita / Saga Univ. (D2)

Collaborators

Tomohiro Fujita / Ochanomizu Univ.

Tomo Takahashi / Saga Univ.

Work in progress

21th Saga-Yonsei partnership

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Large-scale structure (LSS) and Gravity theory

Study gravity theories by using galaxy distribution

The galaxy distribution includes

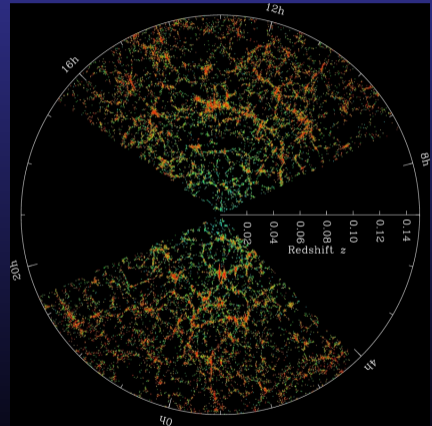
- ★many-body
- ★Baryonic interaction and ...

very complicated

introduce a bias model to evade complicated issues

$$\text{i.e. } \delta_g = \mathcal{F}[\delta_{\text{Gravity}}, \delta_{\text{Linear}}]$$

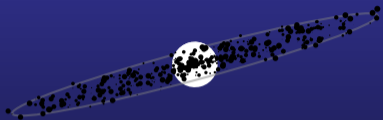
→ What is the correct bias model?



Credit: M. Blanton and the Sloan Digital Sky Survey.

Bias model

DARK MATTER ONLY



relying on the fluid equation:

$$\frac{\partial}{\partial \eta} \delta + \nabla \cdot [(\delta + 1)\mathbf{V}] = 0,$$

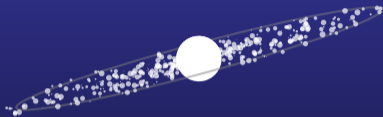
$$\frac{\partial}{\partial \eta} \mathbf{V} + \frac{1}{2} + (\mathbf{V} \cdot \nabla)\mathbf{V} + \frac{3}{2}\nabla\varphi = 0,$$

$$\Delta\varphi = \delta$$

⇒ Solution: δ

One of the simplest bias model: $\delta_g = b \cdot \delta$ (b is a bias parameter).

GALAXY



relying on the **modified** fluid equation:

$$\frac{\partial}{\partial \eta} \delta_g + \nabla \cdot [(\delta_g + 1)\mathbf{V}_g] = \text{source term (1)},$$

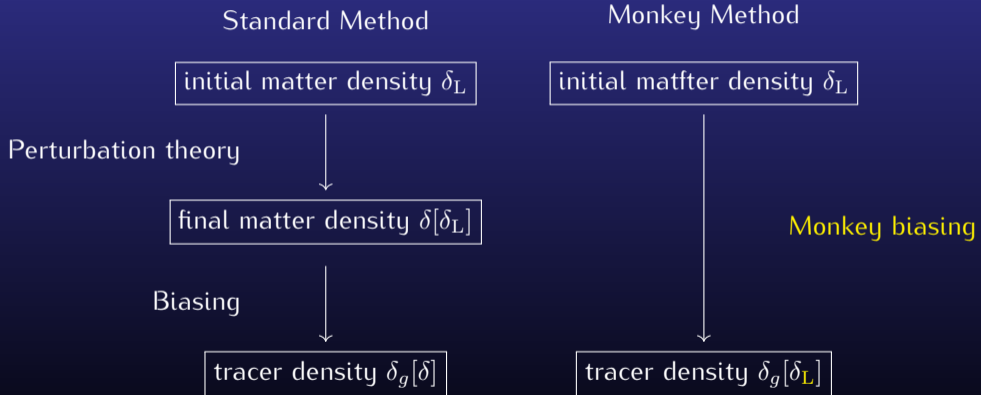
$$\frac{\partial}{\partial \eta} \mathbf{V}_g + \frac{1}{2} + (\mathbf{V}_g \cdot \nabla)\mathbf{V}_g + \frac{3}{2}\nabla\varphi = \text{source term (2)},$$

$$\Delta\varphi = \delta_g$$

⇒ Solution: $\delta_{g(\text{tracer})}$ **(UNKNOWN)**

Monkey bias

Fujita and Vlah., 2003.10114



We need galaxy distribution for testing gravity!!

How can we predict galaxy distribution?

1. We cannot predict the galaxy distribution δ_g .
2. We can predict the dark matter distribution δ .



We need a bias model to obtain δ_g

Why we introduce Monkey bias?

1. Monkey bias doesn't require a detailed gravity theory to be specified.
2. Monkey bias can obtain very general condition by **using consistency relation**.

Monkey bias method (1) Fujita and Vlah., 2003.10114

What are the equations that determine the biased Tracer?

Consider fluid equations ($\theta := \nabla \cdot \mathbf{V}$).

$$\partial_\eta \delta + \sim \delta + \sim \theta \approx \sim \delta \theta + \sim \partial_i \delta \frac{\partial_i}{\partial^2} \theta, \quad \partial_\eta \theta + \sim \delta + \sim \theta \approx \sim \frac{\partial_i \partial_j}{\partial^2} \theta \frac{\partial_i \partial_j}{\partial^2} \theta$$

some number

More generally,

$$\rightarrow \partial_\eta \Delta + \sim \Delta \approx \sim \Delta \Delta \sim \partial_i \Delta \frac{\partial_i}{\partial^2} \Delta \sim \frac{\partial_i \partial_j}{\partial^2} \Delta \frac{\partial_i \partial_j}{\partial^2} \Delta \quad (\Delta = \delta \text{ or } \theta)$$

1st order : $\delta^{(1)} = \delta_L = D(\eta) \delta_{L0}, \quad \theta^{(1)} \propto \delta_L \quad (\partial_\eta \delta_L \propto \delta_L)$

2nd order : $\delta^{(2)} = \sim \delta_L \delta_L + \sim \partial_i \delta_L \frac{\partial_i}{\partial^2} \delta_L + \sim \frac{\partial_i \partial_j}{\partial^2} \delta_L \frac{\partial_i \partial_j}{\partial^2} \delta_L$

Monkey bias method (2) Fujita and Vlah., 2003.10114

$$\delta_g = a\delta_L + b_1\delta_L^2 + b_2\partial_i\delta_L\frac{\partial_i}{\partial^2}\delta_L + b_3\frac{\partial_i\partial_j}{\partial^2}\delta_L\frac{\partial_i\partial_j}{\partial^2}\delta_L + \dots$$



Fourier space

$$\delta_g(\mathbf{k}) = a\delta_L(\mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[b_1 + b_2\frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3\frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\mathbf{p}_1)\delta_L(\mathbf{p}_2) + \dots$$

a, b_1, b_2, b_3, \dots include bias and gravity's information (In general, depend on scale).

Connections between the individual bias parameters, a, b_1, b_2, b_3 ?

Can analytically determine the bias parameters?

Monkey bias method (2) Fujita and Vlah., 2003.10114

$$\delta_g = a\delta_L + b_1\delta_L^2 + b_2\partial_i\delta_L\frac{\partial_i}{\partial^2}\delta_L + b_3\frac{\partial_i\partial_j}{\partial^2}\delta_L\frac{\partial_i\partial_j}{\partial^2}\delta_L + \dots$$



Fourier space

$$\delta_g(\mathbf{k}) = a\delta_L(\mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[b_1 + b_2\frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3\frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\mathbf{p}_1)\delta_L(\mathbf{p}_2) + \dots$$

a, b_1, b_2, b_3, \dots include bias and gravity's information (In general, depend on scale).

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Try with consistency relations!!

Consistency relation with *Functional method* (1) Valageas., 1211.12364

Considering δ_{L0} as Gaussian,

$$\begin{aligned}\left\langle \delta_{L0}(x) \cdot \underbrace{\rho}_{\rho[\delta_{L0}]} \right\rangle &= \int \mathcal{D}\delta_{L0}(x') \delta_{L0}(x) \left[\rho \cdot \exp(-\delta_{L0}^2/2\sigma) \right](x') \\ &= -\sigma(x) \int \mathcal{D}\delta_{L0}(x') \rho(x') \frac{\mathcal{D}[\exp(-\delta_{L0}^2/2\sigma)](x')}{\mathcal{D}\delta_{L0}(x)} \\ &= \sigma(x) \int \mathcal{D}\delta_{L0}(x') \frac{\mathcal{D}\rho(x')}{\mathcal{D}\delta_{L0}(x)} \left[\exp(-\delta_{L0}^2/2\sigma) \right](x') \\ &= \sigma(x) \left\langle \frac{\mathcal{D}\rho}{\mathcal{D}\delta_{L0}(x)} \right\rangle\end{aligned}$$

In Fourier space

$$\langle \delta_{L0}(\mathbf{k}) \cdot \rho \rangle = P_{L0}(k) \left\langle \frac{\mathcal{D}\rho}{\mathcal{D}\delta_{L0}(-\mathbf{k})} \right\rangle, \quad \langle \delta_{L0}(\mathbf{k}_1) \delta_{L0}(\mathbf{k}_2) \rangle = (2\pi)^3 \delta_{\mathbf{D}}(\mathbf{k}_1 + \mathbf{k}_2) P_{L0}(k_1)$$

Consistency relation (2)

$\rho = \delta(\mathbf{k}_1)\delta(\mathbf{k}_2)$ case

$$\frac{\mathcal{D}\delta(\mathbf{k}')}{\mathcal{D}\delta_{L0}(\mathbf{k})} = ?$$

Consider long mode's change, $\Delta\delta_{L0}(\mathbf{k})$, ($\mathbf{k} \rightarrow 0$), the effect is:

$$\delta(t, \mathbf{x}) \xrightarrow{\mathcal{D}\delta_{L0}} \delta(t, \mathbf{x} + \Delta\mathbf{x})$$

$$\delta(t, \mathbf{p}) \xrightarrow{\mathcal{D}\delta_{L0}} e^{i\mathbf{p}\cdot\Delta\mathbf{x}}\delta(t, \mathbf{p})$$

What is $\Delta\mathbf{x}$?

Consistency relation (3)

By using velocity linear solution: $\mathbf{v}(\mathbf{k}) = -i(\mathbf{k}/k^2)\partial_\eta\delta_L(\mathbf{k})$

$$\Delta\mathbf{x}(\eta) = \int d\eta \Delta\mathbf{v}(\mathbf{k}) = -i(\mathbf{k}/k^2)D(\eta)\Delta\delta_L(\mathbf{k}),$$

requiring

1. equivalence principle
2. continuity equation $(\partial_\eta\delta + \nabla \cdot [(\delta + 1)\mathbf{V}] = 0)$

Thus long mode changes as

$$e^{i\mathbf{p} \cdot \Delta\mathbf{x}}\delta(\eta, \mathbf{p}) \simeq [1 + i\mathbf{p} \cdot \Delta\mathbf{x}]\delta(\eta, \mathbf{p}) = \left[1 + D(\eta)\frac{\mathbf{k} \cdot \mathbf{p}}{k^2}\Delta\delta_{L0}(\mathbf{k})\right]\delta(\eta, \mathbf{p})$$

$$\therefore \frac{\mathcal{D}\delta(\eta, \mathbf{p})}{\mathcal{D}\delta_{L0}(\mathbf{k})} = D(\eta)\frac{\mathbf{k} \cdot \mathbf{p}}{k^2}\delta(\eta, \mathbf{p})$$

Consistency relation (4)

$$\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\eta_1, \mathbf{k}_1) \delta(\eta_2, \mathbf{k}_2) \rangle = P_L(k) \left\langle \frac{D\delta(\mathbf{k}_1)\delta(\mathbf{k}_2)}{D\delta_{L0}(-\mathbf{k})} \right\rangle$$

$$\Rightarrow \langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\eta_1, \mathbf{k}_1) \delta(\eta_2, \mathbf{k}_2) \rangle_{k \rightarrow 0} = -P_L(k) \times \mathbf{k} \cdot \left[\frac{D(\eta_1)\mathbf{k}_1}{k^2} + \frac{D(\eta_2)\mathbf{k}_2}{k^2} \right] \langle \delta(\mathbf{k}_1)\delta(\mathbf{k}_2) \rangle$$

$$\xrightarrow{\eta = \eta_1 = \eta_2} \langle \delta_{L0}(\mathbf{k}) \cdot \delta(\mathbf{k}_1)\delta(\mathbf{k}_2) \rangle_{k \rightarrow 0} = -P_L(k)D(\eta) \times \mathbf{k} \cdot \left(\frac{\mathbf{k}_1 + \mathbf{k}_2}{k^2} \right) \langle \delta(\mathbf{k}_1)\delta(\mathbf{k}_2) \rangle = 0$$

For the general density contrast δ : consistency relation

$$\begin{aligned} & \lim_{k_j \rightarrow 0} \left\langle \prod_j \delta^{(\alpha_j)}(\mathbf{k}_j) \cdot \prod_i \delta^{(\alpha'_i)}(\mathbf{k}_i) \right\rangle \\ &= \prod_j \left[-P_L^{(\alpha'_j)}(\eta_j, \mathbf{k}_j) \times \sum_i \frac{\mathbf{k}_j \cdot \mathbf{k}_i}{k_j^2} \frac{D(\eta_i)}{D(\eta_j)} \right] \times \left\langle \prod_i \delta^{(\alpha_i)}(\eta_i, \mathbf{k}_i) \right\rangle \end{aligned}$$

Bias constraining Fujita and Vlah., 2003.10114

Let's try to constrain bias parameters!

1. Now, we have unknown bias parameters: a, b_1, b_2, b_3 .
2. If bias parameters are constrained, we can obtain galaxy distribution: δ_g .

$$\delta_g(\mathbf{k}) = a\delta_L(\mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[b_1 + b_2 \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3 \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\mathbf{p}_1) \delta_L(\mathbf{p}_2) + \dots$$

Constraints with equal-time consistency relation (m : dark matter, α, β : galaxies' name)

$$\langle \delta_m(\mathbf{k}) \cdot \delta_\alpha(\mathbf{k}_1) \delta_\beta(\mathbf{k}_2) \rangle_{k \rightarrow 0} = 0$$

$$\langle \delta_m(\mathbf{k}) \cdot \delta_\alpha(\mathbf{k}_1) \delta_\beta(\mathbf{k}_2) \rangle \simeq \int_{\mathbf{k}_1=\mathbf{p}_1+\mathbf{p}_2} \left[\langle \delta_L(\mathbf{k}) \cdot \delta_\alpha^{(2)}(\mathbf{k}_1) \delta_\beta^{(1)}(\mathbf{k}_2) \rangle + \langle \delta_L(\mathbf{k}) \cdot \delta_\alpha^{(1)}(\mathbf{k}_1) \delta_\beta^{(2)}(\mathbf{k}_2) \rangle \right]$$

$$\begin{aligned}
\left\langle \delta_L(\mathbf{k}) \cdot \delta_\alpha^{(2)}(\mathbf{k}_1) \delta_\beta^{(1)}(\mathbf{k}_2) \right\rangle_{\mathbf{k}_1=\mathbf{p}_1+\mathbf{p}_2} &= a^{(\beta)} \left[b_1^{(\alpha)} + b_2^{(\alpha)} \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3^{(\alpha)} \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \langle \delta_L(\mathbf{k}) \cdot \delta_L(\mathbf{p}_1) \delta_L(\mathbf{p}_2) \delta_L(\mathbf{k}_2) \rangle \\
&= a^{(\beta)} \left[b_1^{(\alpha)} + b_2^{(\alpha)} \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3^{(\alpha)} \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \times (2\pi)^6 P_L(\mathbf{k}) P_L(\mathbf{k}_2) \\
&\quad \times [\delta_D(\mathbf{k} + \mathbf{p}_1) \delta_D(\mathbf{p}_2 + \mathbf{k}_2) + \delta_D(\mathbf{k} + \mathbf{p}_2) \delta_D(\mathbf{p}_1 + \mathbf{k}_2)] \\
&\stackrel{k \rightarrow 0}{\simeq} a^{(\beta)} b_2^{(\alpha)} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \times (2\pi)^6 P_L(k) P_L(k_2) \delta_D(\mathbf{k} + \mathbf{p}_1) \delta_D(\mathbf{p}_2 + \mathbf{k}_2)
\end{aligned}$$

$$\begin{aligned}
\left\langle \delta_L(\mathbf{k}) \cdot \delta_\alpha^{(1)}(\mathbf{k}_1) \delta_\beta^{(2)}(\mathbf{k}_2) \right\rangle_{\mathbf{k}_2=\mathbf{p}_1+\mathbf{p}_2} &\stackrel{k \rightarrow 0}{\simeq} a^{(\alpha)} b_2^{(\beta)} \frac{\mathbf{k} \cdot \mathbf{k}_1}{k^1} \times (2\pi)^6 P_L(k) P_L(k_1) \delta_D(\mathbf{k} + \mathbf{p}_1) \delta_D(\mathbf{p}_2 + \mathbf{k}_1) \\
&\stackrel{\mathbf{k}_1+\mathbf{k}_2=0}{\rightarrow} - a^{(\alpha)} b_2^{(\beta)} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \times (2\pi)^6 P_L(k) P_L(k_2) \delta_D(\mathbf{k} + \mathbf{p}_1) \delta_D(\mathbf{p}_2 + \mathbf{k}_1)
\end{aligned}$$

$$\therefore \left\langle \delta_m(\mathbf{k}) \cdot \delta_\alpha(\mathbf{k}_1) \delta_\beta(\mathbf{k}_2) \right\rangle_{k \rightarrow 0} \simeq \left[a^{(\beta)} b_2^{(\alpha)} - a^{(\alpha)} b_2^{(\beta)} \right] \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} P_L(k) P_L(k_2)$$

equal-time consistency relation

$$\langle \delta_m(\mathbf{k}) \cdot \delta_\alpha(\mathbf{k}_1) \delta_\beta(\mathbf{k}_2) \rangle_{k \rightarrow 0} = 0$$

by using this,

$$a^{(\beta)} b_2^{(\alpha)} - a^{(\alpha)} b_2^{(\beta)} = 0 \quad \iff \quad \frac{b_2}{a} = \text{Constant} =: \mathcal{C}_b$$

The condition, satisfied for arbitrary galaxy.

$$b_2 = \mathcal{C}_b a$$

Velocity (momentum) consistency relation?

Rizzo et al., 1606.03708

Consider non-equal time consistency relation

$$\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\eta_1, \mathbf{k}_1) \delta(\eta_2, \mathbf{k}_2) \rangle_{k \rightarrow 0} = -P_L(k) \times \mathbf{k} \cdot \left[\frac{D(\eta_1) \mathbf{k}_1}{k^2} + \frac{D(\eta_2) \mathbf{k}_2}{k^2} \right] \langle \delta(\eta_1, \mathbf{k}_1) \delta(\eta_2, \mathbf{k}_2) \rangle$$

doing η_2 derivative:

$$\begin{aligned} & \left\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\eta_1, \mathbf{k}_1) \frac{\partial \delta(\eta_2, \mathbf{k}_2)}{\partial \eta_2} \right\rangle_{k \rightarrow 0} \\ &= -P_L(k) \left\{ \frac{d \log D(\eta_2)}{d \eta_2} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \langle \delta(\mathbf{k}_1) \delta(\mathbf{k}_2) \rangle + \mathbf{k} \cdot \left[\frac{D(\eta_1) \mathbf{k}_1}{k^2} + \frac{D(\eta_2) \mathbf{k}_2}{k^2} \right] \left\langle \delta(\mathbf{k}_1) \frac{\partial \delta(\mathbf{k}_2)}{\partial \eta_2} \right\rangle \right\} \end{aligned}$$

Associating continuity equation: $\partial_\eta \delta = -\nabla \cdot [(1 + \delta)\mathbf{v}]$,

\Rightarrow Momentum $\mathbf{p} := (1 + \delta)\mathbf{v}$ consistency relation?

equal time ($\eta = \eta_1 = \eta_2$) derivative consistency relation (New condition is obtained!)

$$\left\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\eta_1, \mathbf{k}_1) \frac{\partial \delta(\eta_2, \mathbf{k}_2)}{\partial \eta_2} \right\rangle_{k \rightarrow 0} \stackrel{\eta = \eta_1 = \eta_2}{=} -P_L(k) \frac{\dot{D}}{D} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \langle \delta(\mathbf{k}_1) \delta(\mathbf{k}_2) \rangle$$

Can we derive **further restriction** for the bias?

Derivative of density contrast

By using $\partial_\eta \delta_L = \dot{D}/D \delta_L$,

$$\partial_\eta \delta_g(\eta, \mathbf{k}) = A \delta_L(\eta, \mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[B_1 + B_2 \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + B_3 \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\eta, \mathbf{p}_1) \delta_L(\eta, \mathbf{p}_2) + \dots$$

Derivative of density contrast

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remember? $\delta_g(\mathbf{k}) = a \delta_L(\mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[b_1 + b_2 \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3 \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\mathbf{p}_1) \delta_L(\mathbf{p}_2) + \dots$

where $A := \dot{a} + a \dot{D}/D$, $B_i := \dot{b}_i + 2b_i \dot{D}/D$ ($i = 1, 2, 3$) are the bias parameters of $\partial_\eta \delta_g$.

equal time velocity consistency relation

$$\left\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta(\mathbf{k}_1) \frac{\partial \delta(\mathbf{k}_2)}{\partial \eta_2} \right\rangle_{k \rightarrow 0} \stackrel{\eta = \eta_1 = \eta_2}{=} -P_L(k) \frac{\dot{D}}{D} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \langle \delta(\mathbf{k}_1) \delta(\mathbf{k}_2) \rangle$$

$$\left\{ \begin{array}{l} \text{LHS: } \left\langle \delta_{L0}(\eta, \mathbf{k}) \cdot \delta_\alpha(\mathbf{k}_1) \frac{\partial \delta_\beta(\mathbf{k}_2)}{\partial \eta_2} \right\rangle_{k \rightarrow 0} = \left[b_2^{(\alpha)} A^{(\beta)} - a^{(\alpha)} B_2^{(\beta)} \right] \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} P_L(\mathbf{k}) P_L(\mathbf{k}_2) \\ \text{RHS: } -P_L(k) \frac{\dot{D}}{D} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} \langle \delta(\mathbf{k}_1) \delta(\mathbf{k}_2) \rangle = -a^{(\alpha)} a^{(\beta)} \frac{\dot{D}}{D} \frac{\mathbf{k} \cdot \mathbf{k}_2}{k^2} P_L(\mathbf{k}) P_L(\mathbf{k}_2) \end{array} \right.$$

Comparing both term (A, B_i are expanded by a, b_i)

$$a^{(\alpha)} \left[\dot{b}_2^{(\beta)} + 2b_2^{(\beta)} \dot{D}/D \right] - b_2^{(\alpha)} \left[\dot{a}^{(\beta)} + a^{(\beta)} \dot{D}/D \right] = a^{(\alpha)} a^{(\beta)} \dot{D}/D$$

Considering $\alpha = \beta$ and applying $b_2 = \mathcal{C}_b a$,

$$a \left[\dot{b}_2 + 2b_2 \dot{D}/D \right] - b_2 \left[\dot{a} + a \dot{D}/D \right] = a^2 \dot{D}/D$$

$$\Rightarrow a \partial_\eta (\mathcal{C}_b a) D + \mathcal{C}_b a^2 \dot{D} - a \dot{a} \mathcal{C}_b D = a^2 \dot{D}$$

$$\Rightarrow \partial_\eta [(\mathcal{C}_b - 1)D] = 0$$

$$\therefore \mathcal{C}_b - 1 \propto \frac{1}{D} \quad \text{or} \quad \mathcal{C}_b = 1.$$

\mathcal{C}_b condition

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Considering $\alpha = \beta$ and applying $b_2 = \mathcal{C}_b a$,

$$a \left[\dot{b}_2 + 2b_2 \dot{D}/D \right] - b_2 \left[\dot{a} + a \dot{D}/D \right] = a^2 \dot{D}/D$$

$$\Rightarrow a \partial_\eta (\mathcal{C}_b a) D + \mathcal{C}_b a^2 \dot{D} - a \dot{a} \mathcal{C}_b D = a^2 \dot{D}$$

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\mathcal{C}_b condition

$$\mathcal{C}_b - 1 \propto \frac{1}{D} \quad \text{or} \quad \mathcal{C}_b = 1.$$

$$\delta_g(\mathbf{k}) = a \delta_L(\mathbf{k}) + \int_{\mathbf{k}=\mathbf{p}_1+\mathbf{p}_2} \left[b_1 + \mathcal{C}_b a \frac{\mathbf{p}_1 \cdot \mathbf{p}_2}{p_1^2} + b_3 \frac{(\mathbf{p}_1 \cdot \mathbf{p}_2)^2}{p_1^2 p_2^2} \right] \delta_L(\mathbf{p}_1) \delta_L(\mathbf{p}_2) + \dots$$

SUMMARY

- ▶ Consistency relations give general conditions and can be derived with a few conditions. (But they require continuity equation.)
- ▶ By considering generalized fluid equation (for the biased tracer), the perturbative solution can be obtained.
- ▶ By using (density, velocity) consistency relations, we derived the conditions for the bias parameters.